Sherry (Yuxuan) Chen

yuxuansherry.chen@mail.utoronto.ca

https://github.com/sherrychen127

sherry-chen-engsci127
sherrychen127.github.io

Education

2021 – 2023	University of Toronto Institute of Aerospace Studies MASc. in Aerospace Engineering , cGPA: 4.0/4.0
	Autonomous Space Robotics Lab (ASRL) Thesis: <i>Self-Supervised Feature Learning for Long-Term Visual Localization</i> Supervisor: Timothy D. Barfoot
2016 – 2021	University of Toronto BASc. in Engineering Science , Robotics major, cGPA: 3.72/4.0, mGPA: 3.94/4.0 Artificial Intelligence minor
	Thesis: Self-Supervised Learning with Iterative Clustering for Human Action Videos. Supervisor: Florian Shkurti

Professional Experience

2020.6 - 2021.9	Machine Learning Researcher , University of Toronto <i>Robot, Vision and Learning (RVL) Lab</i> Proposed and implemented a state-of-the-art method for self-supervised video rep learning using PyTorch by iteratively clustering and contrasting embeddings from (published in CVPR 2022)	
2019.5 - 2020.5	Software Engineer Intern , Intel Corporation Participated in the development of a data-driven application in Python for correlati simulation results and silicon testing data for FPGA timing/power analysis. Indep- architected a PostgreSQL database with 1TB of data for scalability.	-
2018.5 - 2018.9	Software Engineer Intern , Thales Canada Transportation Solution Implemented code changes to the On-board Controller software in the Singapore way signaling system. Designed various testing scenarios to validate code changes optimize the functionality of Automatic Train Protection software.	e

Research Publications

- Y. Chen and T. D. Barfoot, "Self-supervised feature learning for long-term metric visual localization," *IEEE Robotics and Automation Letters*, vol. 8, no. 2, pp. 472–479, 2023. *O* DOI: 10.1109/LRA.2022.3227866.
- Y. Chen*, S. H. Khorasgani*, and F. Shkurti, "Slic: Self-supervised learning with iterative clustering for human action videos," in 2022 IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR Oral), 2022, pp. 16 070–16 080. O DOI: 10.1109/CVPR52688.2022.01562.

(*joint first authors)

Scholarships and Awards

2022-2023	Dr Lorne Heuckroth Scholarship in Aerospace Studies
2020-2021	University of Toronto Department of Computer Science Undergraduate Research Award
2016	Dean's Merit Award
2016-2021	University of Toronto Dean's List

Teaching and Services

2023	Teaching Assistant at University of Toronto ROB521 - Mobile Robotics and Perception
2022	Teaching Assistant at University of Toronto APS112 - Engineering Strategies and Practice
2020-2022	Lab Teaching Assistant at University of Toronto ROB301 - Introduction to Robotics
2022	Reviewer for IEEE Robotics and Automation Letters, R-AL 2023

Skills

Languages	Python , C/C++ , MATLAB, Bash, SQL, Julia, Java, VBA, HTML/CSS/Java Script, Prolog, Verilog, ARM assembly, Latex
Libraries	Pytorch, ROS, Tensorflow, OpenCV, Pandas, Numpy, SciPy, Keras, Jupyter
Tools	Git, Gazebo, RViz, postgreSQL, Quartus Prime, perforce, Rational Clearcase, Solidworks

Extracurricular Activities

2019-2020	UTEK Senior Design Director Organized the UTEK (University of Toronto Engineering Competition) Senior Design Competition for senior year engineering students
	aUToronto Autodrive Team (Autonomy Team) Use deep learning to detect traffic lights and signs for a level 4 autonomous vehicle to compete in the GM/SAE Autodrive challenge
2018	Game AI for Orbis Challenge Ranked top 10 and won Bronze Medal at 2018 Orbis Challenge
2017	U of T Taekwondo Competitive team Ranked 1st place in 2017 Toronto Open Taekwondo Championships